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13. ABSTRACT (Maximum 200 words)  This document describes the development of the Hydrodynamic Power Semiconductor Device Simulator (HPSDS), which solves the quantum mechanical hydrodynamic balance equations for the electrons and holes, along with the Poisson equation, for a two-dimensional device. The program will compute the electrostatic potential, electron and hole densities, recombination rate, electron and hole velocities, current densities, electron and hole temperatures, and other quantities of interest as functions of applied bias. The program allows extensive analysis of unipolar, bipolar, and heterostructure devices. Power devices such as thyristor and other four or five terminal devices are treated under all possible operating conditions. Both steady state and transient operating conditions can be considered. Because of the inclusion of energy balance equations and heat diffusion equation, accurate high-field characteristics can be obtained with this program. Silicon and Gallium Arsenide are the primary materials considered here, although other materials can be included if the user supplies the necessary material data file. In particular, wide band-gap materials such as Silicon Carbide and Gallium Nitride are included also.  In addition to the high-power aspects, high-frequency devices are also simulated. These include superlattice based negative differential resistance devices an resonant tunneling diodes.					
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# ***Power Semiconductor Simulation***

## **Final Report**

March 30, 2001

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### **Abstract**

This document describes the development of the Hydrodynamic Power Semiconductor Device Simulator (HPSDS), which solves the quantum mechanical hydrodynamic balance equations for the electrons and holes, along with the Poisson equation, for a two-dimensional device. The program will compute the electrostatic potential, electron and hole densities, recombination rate, electron and hole velocities, current densities, electron and hole temperature, and other quantities of interest as functions of applied bias. The program allows extensive analysis of unipolar, bipolar, and heterostructure devices. Power devices such as thyristor and other four or five terminal devices are treated under all possible operating conditions. Both steady state and transient operating conditions can be considered. Because of the inclusion of energy balance equations and heat diffusion equation, accurate high-field characteristics can be obtained with this program.

Silicon and Gallium Arsenide are the primary materials considered in this program, although other materials can be included if the user supply the necessary material data file. In particular, wide band-gap materials such as Silicon Carbide and Gallium Nitride are being currently added to the materials library of the code. All materials related parameters are contained within a single subroutine, so that it is easily modified by the user to suit his own situation. For the theoretical basis and numerical implementation of the code, the reader is directed to the references. Materials parameters are also discussed in the references.

## **1. Introduction**

### **1.1 Scope**

This document reports on the project entitled "Power Semiconductor Simulation". The following paragraphs will identify a software system for accurate and computationally efficient codes for simulating high-power semiconductor devices. The codes were developed for use in any parallel-processing environment, which has the Message Passing Interface (MPI), a de-facto standard of parallel programming model.

### **1.2 Objectives**

The goal of this project was to develop a working simulation package for power semiconductor devices, such as large area thyristors, and high frequency devices, such as MESFETs, HEMTs for use in oscillators. Aside from the traditional materials to be simulated such as silicon and gallium arsenide, wide band gap semiconductors like silicon carbide will be simulated because of its good thermal and high voltage properties. The simulation code will be based on scaleable hardware and will be rapidly accessible to DoD researchers.

The project of large-scale numerical simulation of semiconductor devices involves computational tasks that are too demanding for single stand-alone computers and workstations. These tasks are best tackled with massively parallel computers. The numerical codes developed in this project will be specially tailored to suit massively parallel machines.

The code will enable users to perform full electrical and thermal analysis of semiconductor devices under high power/voltage/current operating conditions, thus making it a very useful design and simulation tool for power semiconductor applications as well as applicable to self-heating device studies and temperature dependent model generation.

### **1.3 Approach**

Modeling of power semiconductor devices is more challenging than the modeling of ordinary semiconductor devices in that the former involves not only charge transport but also thermal transport in the devices. Further, the conduction of electricity is coupled with the conduction of heat. Thus the modeling/simulation of power devices depends upon the solution of a set of coupled nonlinear partial differential equations, the Poisson equation, the current continuity equations, and the semiconductor transport equations, as well as the heat diffusion equation, subject to the appropriate initial and boundary conditions. The task of solving such a complicated system of equations entails extremely high demand for computing resources, both in terms of CPU cycles and memory. Massively parallel hardware and corresponding software will be needed to accomplish such a task.

## 1.4 Major Program Elements

The package contains several functional blocks, each of which is designed to perform a certain task. Each block is made of many program units, which perform sub-tasks. The program units have one or more subroutines or functions. In addition, a library consisting of commonly used tools are attached, along with several modeling drivers. The code is written in FORTRAN-90 language.

The blocks are:

Control (CF),  
Definitions (DF),  
Discretization (DS),  
Devices (DV),  
Local Quantities (LC),  
Materials Parameters (MT).

The following is a complete list of the program units in each functional block. All the units are coded in FORTRAN-90 at the present time.

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The blocks are:

Control (CT);  
Definitions (DF);  
Discretization (DS);  
Devices (DV);  
Local Quantities (LC);  
Materials Parameters (MT).

The following is a complete list of the program units in each functional block. All the units are coded in FORTRAN 90 at the present time.

CT\_ADT  
CT\_DF  
CT\_ENERG  
CT\_PARTI  
CT\_POISS  
DF\_ENERG  
DF\_MOMEN  
DF\_PARTI  
DF\_POISS  
DS\_CARRIER\_DENSITY

DS\_CARRIER\_TEMPR  
DS\_CHEMICAL\_POTENTIAL  
DS\_CURRENT\_DENSITY  
DS\_DOPEN\_DENSITY  
DS\_ENERGY\_DENSITY  
DS\_ENERGY\_FLOW\_DENSITY  
DS\_ENERGY\_RATE  
DS\_EQUI\_EQS  
DS\_INVERSE\_MASS  
DS\_NPARA  
DS\_NPARA\_CURRENT  
DS\_NPARA\_POTENTIAL  
DS\_NPARA\_TEMPR  
DS\_PARTICLE\_RATE  
DS\_PHASE\_VELOCITY  
DS\_POTENTIAL  
DS\_SCAT\_RATE  
DS\_VELOCITY\_RATE  
DS\_VELOCITY\_TENSOR  
DV\_1D  
DV\_2D  
DV\_BOUND  
DV\_MyBOLISTIC\_1D  
GRID  
HYSOLVER\_UNITS  
HyBE  
LCEQ\_UNITS  
LC\_CARRIER\_DENSITY  
LC\_CHEMPOT  
LC\_CORR\_FUNC  
LC\_CURRENT\_DENSITY  
LC\_ENERGY\_DENSITY  
LC\_ENERGY\_FLOW\_DENSITY  
LC\_ENERGY\_RATE  
LC\_EQUI\_EQS  
LC\_INVERSE\_MASS  
LC\_NPARA  
LC\_NPARA\_CURRENT  
LC\_NPARA\_POTENTIAL  
LC\_NPARA\_TEMPR  
LC\_PARTICLE\_RATE  
LC\_PHASE\_VELOCITY  
LC\_SCAT\_RATE  
LC\_SINGLE\_LT  
LC\_SINGLE\_LT\_IMP  
LC\_SINGLE\_LT\_PH

LC\_VELOCITY\_RATE  
 LC\_VELOCITY\_TENSOR  
 MT\_ADT  
 MT\_AIGAAS  
 MT\_GENER  
 MT\_KANE  
 MT\_PARAB  
 MT\_USER  
 WKSPACE  
 LIB\_ELEMFUN  
 LIB\_IE\_POLATION  
 LIB\_INTG  
 LIB\_INTG\_GAUSS  
 LIB\_MATRIX  
 LIB\_N\_CONST  
 LIB\_P\_CONST  
 LIB\_ROOT  
 LIB\_VECP

## 2. Major Tasks

The following is a list of major tasks with the above observation in mind.

1. Parallelization of existing code for ballistic diode.
2. Single particle, time-independent code implemented
3. Modification of code to p-n diode and then power diode.
4. Single particle, time independent code parallelized
5. Single particle, time dependent code implemented
6. Modification of code for multilayer devices
7. Many-body, time independent code implemented
8. Single particle, time dependent code parallelized
9. Interface code development
10. Many-body, time independent code parallelized
11. Many-body, time-dependent code implemented
12. Single particle, time dependent, full band structure code implemented
13. Many-body, time dependent code parallelized.

## 3. Major Accomplishments

### Schedule of Events

The following schedule reflects the schedule and status of the major tasks outlined above.

Module/Tasks	Expected Completion	Actual Completion
task 1	1/97	1/97
task 2	3/97	3/97
task 3	7/97	7/97

task 4	10/97	10/97
task 5	12/97	12/97
task 6	3/98	3/98
task 7	6/98	4/98
task 8	6/98	6/98
task 9	9/98	8/98
task 10	12/98	12/98
task 11	5/99	3/99
task 12	12/99	3/00
task 13	12/99	5/00

## 5. Alpha test summary

The following is a summary of the milestones and metrics demonstrated at the off-site CEN-2 Alpha testing conducted at Wright-Patterson AFB, on April 14, 1998.

- 63% speed-up achieved with 16 processors.
- MPI used on SGI Origin 2000 and SGI-PCA supercomputers.
- Now in process of moving parallel code to IBM SP-2.
- Reasonable load balance achieved.

Objective	Required	Observed
Scaled Speedup (16 nodes)	40 %	63%
% code in high level language	80 %	100 %
Number of HPC platforms software will run on.	2	2
# of validations per week	4 or more	4
User computer expertise required.(1-10)	Required = 2 (no GUI) 1=GUI, 5= need to modify source code each run.	2
Major error & % fixable per week.	10, 80 %	5, 100%
% Of software allows for interactive processing.	User specifies input and waits for output in a non real-time mode.	User specifies input and waits for output in a non real-time mode.
# of validations on full code	1 per 2 months	1 per 2 months
% of required external code interfaces completed	Greater or equal to 60%	60 %
% Of last validations that were accurate and valid.	60 %	100 %
# Of potential users exposed to new software capability through problems solved for	Greater or equal to 10	10

them.		

The parameters that can be calculated by computation method are summarized in the next table:

Carrier density	Yes
Carrier temperature	Yes
Electrostatic potential	Yes
Electric field	Yes
Current and current density	Yes

All outputs currently viewed with third party graphics visualization software.

## 6. Beta Test Results

Objective (CTP)		Beta Test
Scaled Speedup	REQ	50% on 32 processors
	OBS	
Scaled Speedup	REQ	Reduces clock time 16x or > on 32 processors
	OBS	
% code uses standard higher order languages, etc	REQ	90% or >
	OBS	
Number of HPC platforms software will run on with valid results.	REQ	2
	OBS	
4 or more validation testes on full code/month	REQ	Yes
	OBS	
Levels of users expertise software provides.	REQ	1
	OBS	
# major errors or < each week and % fixable	REQ	2, 100% within 2 workdays
	OBS	
# data/sets/user scenarios tested/week	REQ	4 or more
	OBS	
% of possible useful output parameters provided	REQ	90%
	OBS	



% of required external code interfaces completed	REQ	80% or greater
	OBS	
% of last 10 software runs produced accurate, valid output	REQ	80%
	OBS	
# of new users added to CTA's HPC community over last year.	REQ	15 or more
	OBS	

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